

1111: Linear Algebra I

Dr. Vladimir Dotsenko (Vlad)

Lecture 21

Examples of linear maps and coordinate changes

Example 1. Let P_n be the vector space of all polynomials in one variable x of degree at most n . Then there is a function $\varphi: P_n \rightarrow P_{n+1}$ that maps every polynomial $f(x)$ to $xf(x)$. (Note that the target of φ has to be different, since multiplying by x increases degrees). This function is a linear map, which we can check in the same way as we did in previous class.

Example 2. Let P_n be the vector space of all polynomials in one variable x of degree at most n . Then we can define both a function $\psi: P_n \rightarrow P_{n-1}$ that maps every polynomial $f(x)$ to $f'(x)$, and a function $\hat{\psi}: P_n \rightarrow P_n$ that maps every polynomial $f(x)$ to $f'(x)$ (since the degree of the derivative of a polynomial of degree at most n is at most $n-1$). These functions are linear maps, which we can check in the same way as in previous class. In fact, $\hat{\psi}$ is a linear transformation, since it is a map from P_n to itself.

Example 3. Consider the vector space M_2 of all 2×2 -matrices. Let us define a function $\alpha: M_2 \rightarrow M_2$ by the formula $\alpha(X) = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} X$. Let us check that this map is a linear transformation. Indeed, by properties of matrix products

$$\begin{aligned}\alpha(X_1 + X_2) &= \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} (X_1 + X_2) = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} X_1 + \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} X_2 = \alpha(X_1) + \alpha(X_2), \\ \alpha(cX) &= \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} (cX) = c \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} X = c\alpha(X).\end{aligned}$$

Example 4. Let us consider the linear map φ from Example 1, and assume $n = 2$. Let us take the bases $e_1 = 1, e_2 = x, e_3 = x^2$ of P_2 , and the basis $f_1 = 1, f_2 = x, f_3 = x^2, f_4 = x^3$ of P_3 , and compute $A_{\varphi, e, f}$. Note that $\varphi(e_1) = x \cdot 1 = x = f_2$, $\varphi(e_2) = x \cdot x = x^2 = f_3$, and $\varphi(e_3) = x \cdot x^2 = x^3 = f_4$. Therefore

$$A_{\varphi, e, f} = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Example 5. Let us consider the linear maps ψ and $\hat{\psi}$ from Example 2, and assume $n = 3$. Let us take the bases $e_1 = 1, e_2 = x, e_3 = x^2, e_4 = x^3$ of P_3 , and the basis $f_1 = 1, f_2 = x, f_3 = x^2$ of P_2 , and let us compute $A_{\psi, e, f}$ and $A_{\hat{\psi}, e}$. Note that $\psi(e_1) = 1' = 0$, $\psi(e_2) = x' = 1 = f_1$, $\psi(e_3) = (x^2)' = 2x = 2f_2$, and $\psi(e_4) = (x^3)' = 3x^2 = 3f_3$, and that $\hat{\psi}(e_1) = 1' = 0$, $\hat{\psi}(e_2) = x' = 1 = e_1$, $\hat{\psi}(e_3) = (x^2)' = 2x = 2e_2$, and $\hat{\psi}(e_4) = (x^3)' = 3x^2 = 3e_3$. Therefore

$$A_{\psi, e, f} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

and

$$A_{\hat{\psi}, \mathbf{e}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Example 6. Let us look at the linear map α from Example 3. We consider the basis of matrix units in M_2 : $\mathbf{e}_1 = E_{11}$, $\mathbf{e}_2 = E_{12}$, $\mathbf{e}_3 = E_{21}$, $\mathbf{e}_4 = E_{22}$. We have

$$\alpha(\mathbf{e}_1) = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} = \mathbf{e}_1 + \mathbf{e}_3,$$

$$\alpha(\mathbf{e}_2) = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} = \mathbf{e}_2 + \mathbf{e}_4,$$

$$\alpha(\mathbf{e}_3) = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \mathbf{e}_1,$$

$$\alpha(\mathbf{e}_4) = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \mathbf{e}_2,$$

so

$$A_{\alpha, \mathbf{e}} = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}.$$

Example 7. Let us take two bases of \mathbb{R}^2 : $\mathbf{e}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $\mathbf{e}_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, and $\mathbf{f}_1 = \begin{pmatrix} 7 \\ 5 \end{pmatrix}$, $\mathbf{f}_2 = \begin{pmatrix} 4 \\ 3 \end{pmatrix}$. Suppose that the matrix of a linear transformation $\varphi: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ relative to the first basis is $\begin{pmatrix} 4 & 0 \\ 0 & 3 \end{pmatrix}$. Let us compute its matrix relative to the second basis. For that, we first compute the transition matrix $M_{\mathbf{e}, \mathbf{f}}$. We have

$$\mathbf{f}_1 = \begin{pmatrix} 7 \\ 5 \end{pmatrix} = 5\mathbf{e}_1 + 2\mathbf{e}_2,$$

$$\mathbf{f}_2 = \begin{pmatrix} 4 \\ 3 \end{pmatrix} = 3\mathbf{e}_1 + \mathbf{e}_2,$$

so

$$M_{\mathbf{e}, \mathbf{f}} = \begin{pmatrix} 5 & 3 \\ 2 & 1 \end{pmatrix},$$

and

$$M_{\mathbf{e}, \mathbf{f}}^{-1} = \begin{pmatrix} -1 & 3 \\ 2 & -5 \end{pmatrix}.$$

Therefore

$$A_{\varphi, \mathbf{f}} = M_{\mathbf{e}, \mathbf{f}}^{-1} A_{\varphi, \mathbf{e}} M_{\mathbf{e}, \mathbf{f}} = \begin{pmatrix} -1 & 3 \\ 2 & -5 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 5 & 3 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} -2 & -3 \\ 10 & 9 \end{pmatrix}.$$

Computing Fibonacci numbers

Fibonacci numbers are defined recursively: $f_0 = 0$, $f_1 = 1$, $f_n = f_{n-1} + f_{n-2}$ for $n \geq 2$, so that this sequence starts like this:

$$0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144, \dots$$

Next time we shall discuss how to derive a formula for these using linear algebra.