## MA 1111: Linear Algebra I

Selected answers/solutions to the assignment for November 23, 2018

1. (a) Looking at the images of basis vectors, we immediately see that the matrix is  $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ . (b) Using transition matrices, we immediately get  $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & -2 \\ 1 & 1 \end{pmatrix}$ . 2. This is a standard exercise on applying transition matrices. Answers are: (a)  $\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ (b)  $\begin{pmatrix} 1 & 0 & 0 \\ 2 & 0 & -1 \\ -1 & 1 & 2 \end{pmatrix}$ 3. (a) Induction: for n = 0 it is true; if  $\begin{pmatrix} 0 & 1 \\ -1 & 3 \end{pmatrix}^k \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} b_k \\ b_{k+1} \end{pmatrix}$ , then  $\begin{pmatrix} 0 & 1 \\ -1 & 3 \end{pmatrix}^{k+1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} b_k \\ b_{k+1} \end{pmatrix} = \begin{pmatrix} b_{k+1} \\ 3b_{k+1} - b_k \end{pmatrix} = \begin{pmatrix} b_{k+1} \\ b_{k+2} \end{pmatrix}$ .

(b) Eigenvalues are roots of  $t^2 - 3t + 1 = 0$ , i.e.  $\lambda_1 = \frac{3+\sqrt{5}}{2}$ ,  $\lambda_2 = \frac{3-\sqrt{5}}{2}$ . The corresponding eigenvectors are  $\begin{pmatrix} 1 \\ \lambda_1 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ \lambda_2 \end{pmatrix}$ . Let  $\mathbf{C} = \begin{pmatrix} 1 & 1 \\ \lambda_1 & \lambda_2 \end{pmatrix}$ . Then  $\mathbf{C}^{-1} \begin{pmatrix} 0 & 1 \\ -1 & 3 \end{pmatrix} \mathbf{C} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$ , so  $\begin{pmatrix} 0 & 1 \\ -1 & 3 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \mathbf{C} \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}^n \mathbf{C}^{-1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{\lambda_1^n - \lambda_2^n}{\lambda_1 - \lambda_2} \\ \frac{\lambda_1^{n+1} - \lambda_2^{n+1}}{\lambda_1 - \lambda_2} \end{pmatrix}$ , and  $\mathbf{b}_n = \frac{\lambda_1^n - \lambda_2^n}{\lambda_1 - \lambda_2}$ .

4. We have  $\det(A - cI_3) = -c^3 + 4c^2 - 5c + 2 = -(c-1)^2(c-2)$ , so the eigenvalues of this matrix are 1 and 2. Solving the systems of equations Ax = x and Ax = 2x, we see that each solution is proportional to, respectively,  $\begin{pmatrix} 1\\1\\0 \end{pmatrix}$  and  $\begin{pmatrix} 2\\1\\1 \end{pmatrix}$ . Thus, there is no basis of eigenvectors,

and the answer to the question on change of coordinates is "no".

5. Note that  $\det(A^3) = (\det(A))^3$ , so if  $A^3 = 0$ , then  $\det(A) = 0$ . According to the previous question, we then have  $A^2 - \operatorname{tr}(A)A = 0$ , so  $A^2 = \operatorname{tr}(A)A$ . If  $\operatorname{tr}(A) = 0$ , we conclude that  $A^2 = 0$ . Otherwise, we have

$$0 = A^3 = A^2 \cdot A = \operatorname{tr}(A)A \cdot A = \operatorname{tr}(A)A^2 = (\operatorname{tr}(A))^2 \cdot A,$$

which for  $tr(A) \neq 0$  implies A = 0.