# MA1112: Linear Algebra II 

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## Lecture 17

Today we shall prove various theorems on quadratic forms stated without proof last week.
Theorem 1. Let $q$ be a quadratic form on a vector space $V$. There exists a basis $f_{1}, \ldots, f_{n}$ of $V$ for which the quadratic form $q$ becomes a signed sum of squares:

$$
q\left(x_{1} f_{1}+\cdots+x_{n} f_{n}\right)=\sum_{i=1}^{n} \varepsilon_{i} x_{i}^{2}
$$

where all numbers $\varepsilon_{i}$ are either 1 or -1 or 0.
Proof. Informally, the slogan behind the proof we shall present is "imitate the Gram-Schmidt procedure". Let us make it precise. We shall argue by induction on $\operatorname{dim} V$, the basis of induction being $\operatorname{dim} V=0$, when the basis is empty, so there is nothing to prove.

Suppose $\operatorname{dim} V=n>0$. There are two cases to consider. First, it might be the case that $q(v)=0$ for all $v$. In this case, any basis would work, with $\varepsilon_{i}=0$ for all $i$.

Otherwise, there exists a vector $v$ such that $q(\nu) \neq 0$. Let us extend it to a basis $e_{1}=v, e_{2}, \ldots, e_{n}$, and look at the symmetric bilinear form $b(v, w)=\frac{1}{2}(q(\nu+w)-q(v)-q(w))$ associated to the quadratic form $q$. We claim that we can change the basis $e_{1}, \ldots, e_{n}$ into a basis $e_{1}^{\prime}, e_{2}^{\prime}, \ldots, e_{n}^{\prime}$ with $e_{1}^{\prime}=e_{1}=v$ and $b\left(e_{i}^{\prime}, e_{1}^{\prime}\right)=0$ for all $i=2, \ldots, n$. Indeed, we can put $e_{i}^{\prime}=e_{i}-\frac{b\left(e_{i}, e_{1}\right)}{b\left(e_{1}, e_{1}\right)} e_{1}$ for $i>1$; here division by $b\left(e_{1}, e_{1}\right)$ is possible since $b\left(e_{1}, e_{1}\right)=q\left(e_{1}\right)=q(\nu) \neq 0$. We can now consider the linear span of $e_{2}^{\prime}, \ldots, e_{n}^{\prime}$ with the bilinear form $q$, and proceed by induction on dimension. Therefore, we can find a basis $f_{2}, \ldots, f_{n}$ of that space with the required property. It remains to note that if we take $e_{1}=\frac{1}{\sqrt{|q(\nu)|}} v$, then we have $q\left(e_{1}\right)= \pm 1$, and also $b\left(e_{1}, e_{i}\right)=0$ for $i>1$, which proves that our quadratic form becomes a signed sum of squares in this basis.

Theorem 2 (Law of inertia). In the previous theorem, the triple $\left(n_{+}, n_{-}, n_{0}\right.$ ), where $n_{ \pm}$is the number of $\varepsilon_{i}$ equal to $\pm 1$, and $n_{0}$ is the number of $\varepsilon_{i}$ equal to 0 , does not depend on the choice of the basis $f_{1}, \ldots, f_{n}$. This triple is often referred to as the signature of the quadratic form $q$.

Proof. Suppose that we have a basis

$$
e_{1}, \ldots, e_{n_{+}}, f_{1}, \ldots, f_{n_{-}}, g_{1}, \ldots, g_{n_{0}}
$$

which produces a system of coordinates where $q$ becomes a signed sum of squares with $n_{+}$of $\varepsilon_{i}$ are equal to $1, n_{-}$ of $\varepsilon_{i}$ are equal to -1 , and $n_{0}$ of $\varepsilon_{i}$ are equal to 0 . Let us look at the corresponding symmetric bilinear form $b$. The reconstruction formula $b(v, w)=\frac{1}{2}(q(v+w)-q(v)-q(w))$ implies that

$$
b\left(x_{1} e_{1}+\cdots+z_{n_{0}} g_{n_{0}}, x_{1}^{\prime} e_{1}+\cdots+z_{n_{0}}^{\prime} g_{n_{0}}\right)=x_{1} x_{1}^{\prime}+\cdots+x_{n_{+}} x_{n_{+}}^{\prime}-y_{1} y_{1}^{\prime}-\cdots-y_{n_{-}} y_{n_{-}}^{\prime} .
$$

By definition, the kernel of a symmetric bilinear form is the space of all vectors $v$ such that $b(\nu, w)=0$ for all $w \in V$. We see that the kernel is defined by a system of equations $b\left(v, e_{i}\right)=b\left(v, f_{j}\right)=b\left(v, g_{k}\right)=0$ for all $i, j, k$, and by direct inspection this system implies that $v$ is a linear combination of the vectors $g_{k}$. This implies that $n_{0}$ is the dimension of the kernel of $b$, and so is independent of any choices.

Suppose now that there are two different bases

$$
e_{1}, \ldots, e_{n_{+}}, f_{1}, \ldots, f_{n_{-}}, g_{1}, \ldots, g_{n_{0}}
$$

and

$$
e_{1}^{\prime}, \ldots, e_{n_{+}^{\prime}}, f_{1}^{\prime}, \ldots, f_{n_{-}^{\prime}}, g_{1}^{\prime}, \ldots, g_{n_{0}}^{\prime}
$$

where $q$ is a signed sum of squares, and $n_{+} \neq n_{+}^{\prime}$, so without loss of generality $n_{+}>n_{+}^{\prime}$. Note that this implies that $n_{-}<n_{-}^{\prime}$. Consider the vectors

$$
e_{1}, \ldots, e_{n_{+}}, f_{1}^{\prime}, \ldots, f_{n_{-}^{\prime}}^{\prime}, g_{1}, \ldots, g_{n_{0}}
$$

The total number of those vectors exceeds the dimension of $V$, so they must be linearly dependent, that is

$$
a_{1} e_{1}+\cdots+a_{n_{+}} e_{n_{+}}+b_{1} f_{1}^{\prime}+\cdots+b_{n_{-}^{\prime}} f_{n_{-}^{\prime}}^{\prime}+c_{1} g_{1}+\cdots+c_{n_{0}} g_{n_{0}}=0
$$

for some scalars $a_{i}, b_{j}, c_{k}$. Let us rewrite it as

$$
a_{1} e_{1}+\cdots+a_{n_{+}} e_{n_{+}}+c_{1} g_{1}+\cdots+c_{n_{0}} g_{n_{0}}=-\left(b_{1} f_{1}^{\prime}+\cdots+b_{n_{-}^{\prime}} f_{n_{-}^{\prime}}^{\prime}\right)
$$

and denote the vector to which both the left hand side and the right hand side are equal to by $\nu$. Then

$$
a_{1}^{2}+\cdots+a_{n_{+}}^{2}=q(\nu)=-b_{1}^{2}-\cdots-b_{n_{-}}^{2},
$$

which implies

$$
a_{1}=\cdots=a_{n_{+}}=b_{1}=\cdots=b_{n_{-}}=0,
$$

and substituting it into

$$
a_{1} e_{1}+\cdots+a_{n_{+}} e_{n_{+}}+b_{1} f_{1}^{\prime}+\cdots+b_{n_{-}^{\prime}} f_{n_{-}^{\prime}}^{\prime}+c_{1} g_{1}+\cdots+c_{n_{0}} g_{n_{0}}=0
$$

we get

$$
c_{1} g_{1}+\cdots+c_{n_{0}} g_{n_{0}}=0
$$

implying of course $c_{1}=\cdots=c_{n_{0}}=0$, which altogether shows that these vectors cannot be linearly dependent, a contradiction.

