Numerical simulation of turbulent jet primary breakup in Diesel engines

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Outline

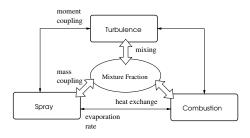


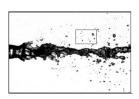
- 2 DNS of Primary Breakup in Diesel Injection
- Phase Transition Modeling
- Turbulence Modeling





Motivation





Spray in Combustion Devices

- Fuel is typically injected as a liquid
- Combustion only in the gaseous phase
- Mixture composition pollutant formation
- Combustion stability
- Need to accurately model Spray Process
- From injection to evaporation

The Challenge of Modeling Spray

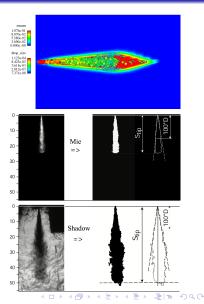
The Spray Model we have

- Empirical nature.
- wide range of Parameters.
- Experiments Calibration.

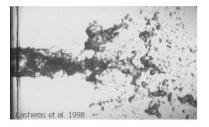
The Experiments are difficult

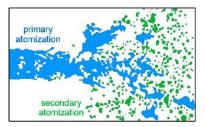
- complex Injection System.
- high Pressure.
- high Temperature.
- Fuel Properties.

Primary Breakup, the beginning of the spray, is particularly poorly understood.



Modeling Spray Primary Breakup



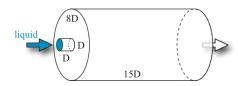


Modeling approach

- split into primary & secondary atomization
- track the complex phase interface geometry during primary breakup
- assume simple phase interface geometry for secondary breakup
- couple with secondary atomization models

DNS Diesel Injection done by Marcus

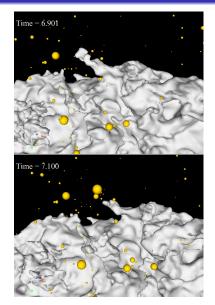
- Injector diameter:
 D = 100 μm
- Flow solver resolution : D/50 = 2.0 μm
- Level Set Solver resolution: D/64 = 1.56 μm
- Injection Velocity: 100 m/s
- Inlet profile: DNS of Re=5000 turbulent pipe
- Density ratio: 850/25
- Viscosity ratio: 1.70E-3/1.78E-5
- Surface tension coefficient: 0.05 N/m

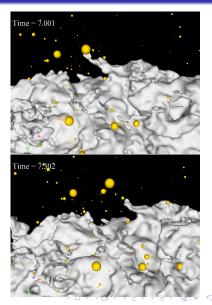


Dr. Marcus Herrmann

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DNS Diesel Injection Results

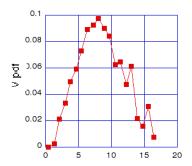


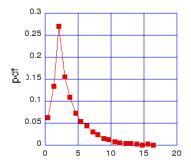


DNS Diesel Injection Results

Drop velocity PDF

Drop size PDF

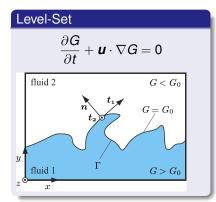




The Governing Equations

Navier-Stokes

$$\frac{\partial \boldsymbol{u}}{\partial t} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} = -\frac{1}{\rho} \nabla \boldsymbol{\rho} + \frac{1}{\rho} \nabla \cdot (\mu (\nabla \boldsymbol{u} + \nabla^{\mathsf{T}} \boldsymbol{u})) + \boldsymbol{g} + \frac{1}{\rho} \boldsymbol{T}_{\sigma}$$
$$\nabla \cdot \boldsymbol{u} = 0$$



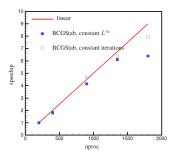
VOF Modification

$$\begin{split} \rho &= \psi \rho_1 + (\mathbf{1} - \psi) \rho_2 \\ \mu &= \psi \mu_1 + (\mathbf{1} - \psi) \mu_2 \end{split}$$

Surface Tension Force

$$\boldsymbol{T}_{\sigma}(\boldsymbol{x}) = \sigma \kappa \delta(\boldsymbol{x} - \boldsymbol{x}_{f})\boldsymbol{n}$$
$$\boldsymbol{n} = \frac{\nabla \boldsymbol{G}}{|\nabla \boldsymbol{G}|}, \ \kappa = \nabla \cdot \boldsymbol{n}$$

Numerics and Performances of two-phase flow solver



Unstructured, Collocated, Finite volume Navier-Stokes Solver

$$\partial_t u + \overline{u} \partial_x u - \partial_{xx} u / Re = 0$$

$$M rac{\mathrm{d} \boldsymbol{u}}{\mathrm{d} t} + \boldsymbol{C}(\overline{u})\boldsymbol{u} + \boldsymbol{D} \boldsymbol{u} = 0$$

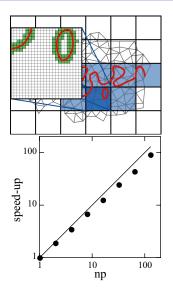
for D = 0, Energy $||u||^2 = u^* M u$ is conserved if and only if

$$\frac{\mathrm{d}}{\mathrm{d}t} \| \boldsymbol{u} \|^2 = -\boldsymbol{u}^* (\boldsymbol{C}(\overline{u}) + \boldsymbol{C}^*(\overline{u})) \boldsymbol{u} = 0$$

 Skew-symmetry of convective derivative : C(u) + C*(u) = 0

- Symmetric, positive-definite diffusive operator
- DNS ⇔ do not want numerical dissipation!

Numerics and Performances of two-phase flow solver

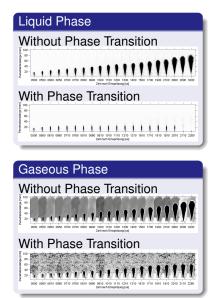


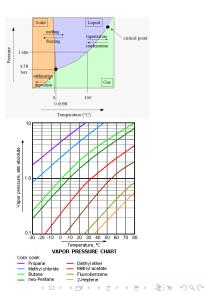
Refined Level Set Grid Method

- Introduce equidistant Cartesian super-grid (blocks)
- Activate (store) only narrow band of blocks
- Active blocks consist of an equi-distant Cartesian fine G-grid
- Activate (store) only narrow band of fine G-grid

⇒ Advantages: low cost of storage, efficient domain decomposition, straightforward parallelization, fast and accurate cartesian solution mothods (5th order WENO, FMM)

Phase Transition Diagram





Phase Transition Models

Introduce a Surface Regression Velocity SP

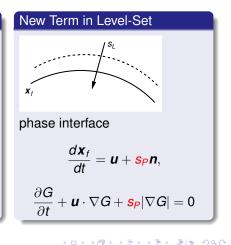
New Term in Navier-Stokes

$$\begin{aligned} \frac{\partial \boldsymbol{u}}{\partial t} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} &= -\frac{1}{\rho} \nabla \rho + \boldsymbol{g} + \frac{1}{\rho} \boldsymbol{\tau}_{\sigma} \\ &+ \frac{1}{\rho} \nabla \cdot (\mu (\nabla \boldsymbol{u} + \nabla^{\mathsf{T}} \boldsymbol{u})) + \frac{1}{\rho} \boldsymbol{\tau}_{\rho} \end{aligned}$$

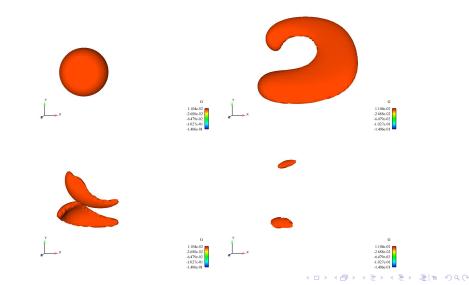
where T_p is the balance force for evaporation.

$$\boldsymbol{T}_{\boldsymbol{
ho}} = (
ho_1 -
ho_2)_{\boldsymbol{SP}} \delta(\boldsymbol{x} - \boldsymbol{x}_f) \boldsymbol{u}$$

 δ is the delta-function.



G field of evaporating Droplet



Numerics for Balance Force Term

Predictor

$$\rho_{c}^{n+1}\boldsymbol{u}_{c}^{*} = \rho_{c}^{n}\boldsymbol{u}_{c}^{n} - \Delta t \sum_{f} \boldsymbol{u}_{c}^{n} \left(\sum_{k} \rho_{k} f_{k}\right) (\boldsymbol{u}_{f} \cdot \boldsymbol{n}_{f}) \boldsymbol{A}_{f} - \Delta t \rho_{c}^{n+1} \left\langle \frac{\nabla \boldsymbol{P}}{\rho_{f}} - \frac{\boldsymbol{T}_{f}}{\rho_{f}} \right\rangle_{f \to c}^{n}$$
(1)

Projection

$$\boldsymbol{u}_{f}^{*} = \left\langle \boldsymbol{u}_{c}^{*} + \Delta t \left\langle \frac{(\nabla P)_{f}}{\rho_{f}} - \frac{\boldsymbol{T}_{f}}{\rho_{f}} \right\rangle_{f \to c}^{n} \right\rangle_{c \to f} - \frac{\Delta t}{\rho_{f}^{n+1}} [(\nabla P)_{f}^{n} - \boldsymbol{T}_{f}^{n+1}]$$
(2)

Corrector

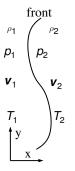
$$\nabla \cdot \left(\frac{(\nabla \delta P_c^{n+1})_f}{\rho_f^{n+1}}\right) = -\nabla \cdot \left(\frac{\boldsymbol{u}_f^*}{\Delta t}\right). \tag{3}$$

$$\boldsymbol{u}_{f}^{n+1} = \boldsymbol{u}_{f}^{*} - \Delta t \left(\frac{(\nabla \delta \boldsymbol{P}_{c}^{n+1})_{f}}{\rho_{f}^{n+1}} \right),$$
(4)

$$\boldsymbol{u}_{c}^{n+1} = \boldsymbol{u}_{c}^{*} + \Delta t \left\langle \frac{(\nabla P)_{f} - \boldsymbol{T}_{f}}{\rho_{f}} \right\rangle_{f \to c}^{n} - \Delta t \left\langle \frac{(\nabla P)_{f} - \boldsymbol{T}_{f}}{\rho_{f}} \right\rangle_{f \to c}^{n+1}$$
(5)

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Stability Analysis of Phase Transition



Equation of Perturbation Motion

$$abla \cdot \boldsymbol{u}' = \mathbf{0} \ , \ \partial \boldsymbol{u}' / \partial t + \boldsymbol{u} \cdot \nabla \boldsymbol{u}' = -1 / \rho \nabla \boldsymbol{p}'$$

Boundary Conditons

$$p'_1 - p'_2 = \mathbf{s}_L(\rho_1 - \rho_2)\zeta(y, t),$$

 $u'_1 - \partial\zeta/\partial t = u'_2 - \partial\zeta/\partial t,$
 $v'_1 + v_1\partial\zeta/\partial t = v'_2 + v_2\partial\zeta/\partial t$

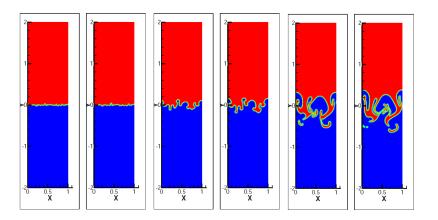
Particular Solution

$$\begin{aligned} u_1' &= Ae^{iky+kx-i\omega t} \\ u_2' &= Be^{iky+kx-i\omega t} + \\ Ce^{iky-i\omega t+i\omega x/v_2} \\ \zeta &= De^{iky-i\omega t} \end{aligned}$$

Charac. Equation for Nontrivial SolutionResult
$$\omega$$
 -1 0 0 ω 0 1 $\frac{ikv_2}{\omega}$ 0 $1 + \frac{i\omega}{\epsilon kv_2}$ $1 + \frac{i\omega}{kv_2}$ $\frac{2ikv_2}{\omega}$ $ik(\epsilon - 1)v_2$ 1 -1 -1

maginary part $\epsilon + \epsilon^{-1} V_2 k$ n front is

Rayleigh-Taylor Instability



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Comparison of DNS, LES and RANS

DNS

$$u(\mathbf{x}, t) = \overline{u} + u'$$

$$\overline{u}(\mathbf{x}, t) = \int \int \int G(\xi - \mathbf{x})u(\xi, t)d\xi$$
RANS

$$u(\mathbf{x}, t) = \overline{u} + u'$$

$$\overline{u}(\mathbf{x}, t) = \lim_{T \to \infty} \frac{1}{T} \int_0^T u(\mathbf{x}, t)dt$$
LES Equations

$$\frac{\partial u_i}{\partial t} + \frac{\partial u_i u_j}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \nu \frac{\partial^2 u_i}{\partial x_j x_j} + \frac{\tau_{ij}}{\partial x_j}$$

subgrid stress model $\tau_{ij} = 2\mu_T S_{ij}$, where $S_{ij} = \frac{1}{2} \left(\frac{\partial \overline{u}_i}{\partial x_j} + \frac{\partial \overline{u}_j}{\partial x_i} \right)$, Smagorinsky eddy viscosity $\mu_T = \rho (C_s \Delta)^2 \sqrt{S_{ij} S_{ij}}$, Smagorinsky coeffcient $0.10 < C_s < 0.24$

Background Information

Energy Cascade

Energy dissipation rate modeled as $\varepsilon \sim \frac{u^2}{t} \sim \frac{u^3}{l} \sim \frac{l^2}{t^3}$

Kolmogorov Scales (Smallest)

length $\eta \equiv (\nu^3 / \varepsilon)^{1/4}$ time $\tau_\eta \equiv (\nu / \varepsilon)^{1/2}$ velocity $u_\eta \equiv (\nu \varepsilon)^{1/4}$

Ratio of Smallest/Largest

$$egin{aligned} &\eta/\mathit{I}_0\sim Re^{-3/4} \ & au_\eta/ au_0\sim Re^{-1/2} \ &u_\eta/u_0\sim Re^{-1/4} \end{aligned}$$

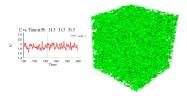
Kolmogorov's hypothesis

At sufficiently high Reynolds number, the small-scale turbulent motion are statistically isotropic.

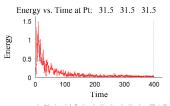
Instead of running 3D full scale DNS, we can test our model on isotropic turbulent environment.

DNS of Isotropic Turbulence in Cubic Box

- $\bullet~Grid:\,128^3\sim2$ Million
- Boundary Condition
 - Periodic in all directions
- Initial Condition
 - $Re_{\lambda} = 120 \sim 200$
- Some Numerics
 - time: Crank-Nicolson
 - spatial: Skew-sym. Con.
 - staggered p and u
 - predictor-corrector
 - preconditioner: Hypre
- Parallelization
 - Domain-decomposition: ParMetis
 - Parallel I/O



Turbulent Energy is decaying!



Linear forced turbulence

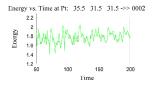
Theory

$$\frac{\partial \boldsymbol{u}}{\partial t} + \boldsymbol{u} \cdot \nabla \boldsymbol{u} = -\nabla p / \rho + \nu \nabla^2 \boldsymbol{u} + \boldsymbol{f}$$

$$\boldsymbol{f} = Q \boldsymbol{u} \text{ where } \boldsymbol{Q} = \epsilon / 3 U^2,$$

$$\epsilon = -\nu < \boldsymbol{u} \cdot \nabla^2 \boldsymbol{u} >,$$

$$U^2 = < \boldsymbol{u} \cdot \boldsymbol{u} > / 3$$



CDP variable	Description	set in Subroutine
Q	Q : scalar for linear forcing	momentum_source_hook
epsilon	ϵ : mean dissipation rate	momentum_source_hook
UU	3 <i>U</i> ² : velocity square	momentum_source_hook

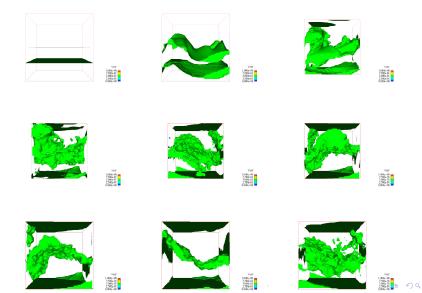
Table: New Variables

F90 implementation

```
do icv = 1,gp%ncv_ib
UU = dot_product(ifp%u(1:3,icv),ifp%u(1:3,icv))
```

Phase Transition Modeling

Phase Interface



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Summary

- DNS for Spray Primary Breakup
- Introduce SP for Phase Transition Modeling

Outlook

- Terabyte DNS
- Modeling Approach
- Cavitation



Norbert Peters.

Turbulent Combustion. Cambridge University Press, 2000.

Marcus Herrmann.

A balanced forced Refined Level Set Grid method for two-phase flows on unstructured flow solver grids. *Journal of Computational Physics*, In Press, Accepted Manuscript, Available online 17 November 2007.